LED Overview and Natural Language Sample Code

The VEX LEDs are treated as digital output devices, and use Digital ports on the Cortex. By turning different LEDs on or off during program execution, they can become useful devices for remotely obtaining feedback from your robot while it is running.

LED Off After Touch
This code has the robot turn on an LED, and then, when the touch sensor is pressed, turn the LED off.

```c
task main ()
{
    turnLEDOn(dgt11); //Turn on LED in Digital Port 11

    untilTouch(dgt12); //Wait until the Touch sensor in Digital Port 12 is pressed

    turnLEDOff(dgt11); //Turn off LED in Digital Port 11
}
```